ZABER

LSA Product
User's Manual
Firmware 5.00 and up

Last Update: December 10 2015
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Disclaimer

Zaber’s devices are not intended for use in any critical medical, aviation, or military applications or situations where a product's use or failure could cause personal injury, death, or damage to property. Zaber disclaims any and all liability for injury or other damages resulting from the use of our products.

Precautions

Zaber's motion control devices are precision instruments and must be handled with care. In particular, moving parts must be treated with care. Avoid axial loads in excess of the rated thrust load, axial and radial impact, dust and other contaminants and damage to the leadscrew thread. These will reduce the performance of the device below stated specifications.

Installation

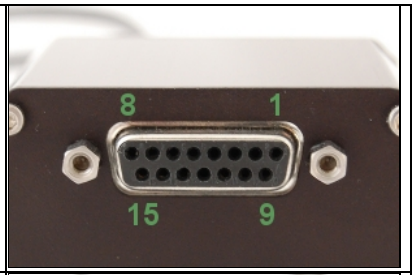
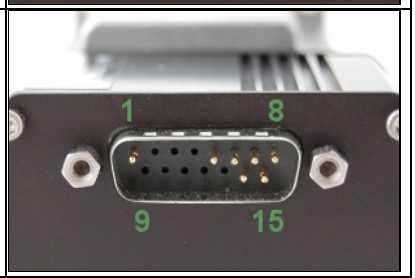
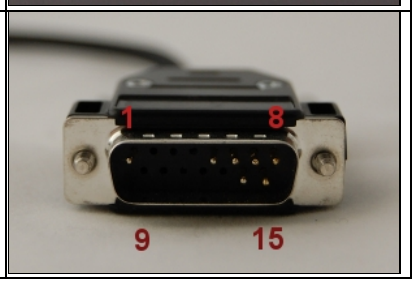
You can mount the LSA stage directly down to a miniature optical breadboard, or to any other surface with M3 x 12.5 thread spacing. Additional M2 threads are also provided on the bottom of the LSA stage for alternate mounting options. See the LSA webpage for dimensions, resolution and other details.

LSA stages can be mounted directly in XY using the screws and dowel pins included with the stages. They can be mounted in XYZ using our AB106 angle bracket.

Operation

This unit is designed to be controlled with any of Zaber's X-Series or A-Series Stepper Motor Controllers. Zaber's controllers and peripherals are designed for ease of use when used together. Optimal settings for each peripheral (such as the default current, speed, acceleration, and limit settings) can be loaded by setting the peripheralid (T:66) on the controller. The peripheral ID is listed as the ID on the peripheral's label. A list of IDs is also available on the ID Mapping page. For more information on device operation, refer to the controller's user manual.

Pinout for D-sub 15 Connectors (A-series and X-Series controllers and peripherals)

A- or X-series controller (female)	
T3 Peripheral (male)	
T4 Peripheral (male)	

Pin #	Function
1	+5V
2	Encoder Error ****
3	*reserved*
4	Away Sensor ***
5	Home Sensor
6	Ground
7	Motor B1
8	Motor A1
9	+5V *
10	Encoder A *
11	Encoder B *

12	Encoder Index **
13	Ground *
14	Motor B2
15	Motor A2

** encoder embedded peripherals only*
*** devices with encoders with index only*
**** devices with away sensors only*
***** devices with linear or direct-reading encoders only*

Motor

The LSA stage uses a size 8 stepper motor.

- 0.24 A / Phase
- 20.4 / phase
- 5.0 mH / phase

- A1 = Red and White
- A2 = Red
- B1 = Green
- B2 = Green and White

Alternate Controllers

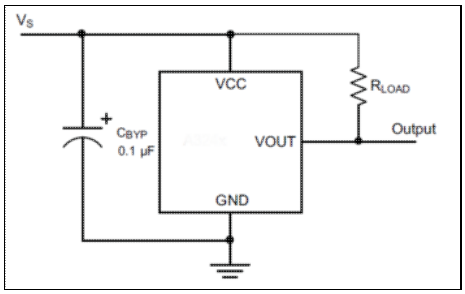
The device may be controlled by any 2-phase stepper motor controller with home sensor input. **Warning: Operating the unit without correctly wiring up the home sensor can cause permanent damage to the unit. We do not recommend using your own controller unless you are familiar with how to control a stepper motor with a hall sensor limit switch.** The following information is provided for reference only. Damage to the actuator or hall sensor due to incorrect wiring is not covered by warranty.

Home Sensor Wiring

A Hall effect sensor is mounted in the device for use as a home sensor. It is part number A1122LUA-T made by Allegro. Click here for data sheet. Your controller should be configured so the stage stops immediately (little deceleration) when the home sensor is triggered.

- Wire colour code:
  - 3.6-24 Vdc input - red
  - Home signal - yellow
  - Ground - black

The Hall sensor has an open-collector output. The default output is high impedance when the Hall sensor is not active. When the sensor detects a magnet, the Hall sensor pulls the output low to ground.



If you are not using a Zaber controller, ensure that your controller has a pull-up resistor on the output line of the Hall sensor as shown in the diagram. The bypass capacitor is optional, but may help to eliminate false triggering in noisy environments. The typical value for the pull-up resistor (R_{LOAD}) is 10k and for the bypass capacitor is 0.1uF to 1uF. The larger the capacitance, the better the noise filtering but the slower the response time.

Warranty and Repair

For Zaber's policies on warranty and repair, please refer to the Ordering Policies

Standard products

Standard products are any part numbers that do not contain the suffix ENG followed by a 4 digit number. Most, but not all, standard products are listed for sale on our website. All standard Zaber products are backed by a one-month satisfaction guarantee. If you are not satisfied with your purchase, we will refund your payment minus any shipping charges. Goods must be in brand new saleable condition with no marks. Zaber products are guaranteed for one year. During this period Zaber will repair any products with faults due to manufacturing defects, free of charge.

Custom products

Custom products are any part numbers containing the suffix ENG followed by a 4 digit number. Each of these products has been designed for a custom application for a particular customer. Custom products are guaranteed for one year, unless explicitly stated otherwise. During this period Zaber will repair any products with faults due to manufacturing defects, free of charge.

How to return products

Customers with devices in need of return or repair should contact Zaber to obtain an RMA form which must be filled out and sent back to us to receive an RMA number. The RMA form contains instructions for packing and returning the device. The specified RMA number must be included on the shipment to ensure timely processing.

Email Updates

If you would like to receive our periodic email newsletter including product updates and promotions, please sign up online at www.zaber.com (news section). Newsletters typically include a promotional offer worth at least $100.

Contact Information

Contact Zaber Technologies Inc by any of the following methods:

Phone	1-604-569-3780 (direct) 1-888-276-8033 (toll free in North America)
Fax	1-604-648-8033
Mail	#2 - 605 West Kent Ave. N., Vancouver, British Columbia, Canada, V6P 6T7
Web	www.zaber.com
Email	Please visit our website for up to date email contact information.

The original instructions for this product are available at http://www.zaber.com/wiki/Manuals/LSA.

Specification	Value	Alternate Unit
Microstep Size (Default Resolution)	0.0238125 µm	
Integrated Controller	No	
Recommended Controller	X-MCB1 (24 V) Recommended	
Repeatability	< 1 µm	< 0.000039 "
Backlash	< 5 µm	< 0.000197 "
Maximum Speed	10 mm/s	0.394 "/s
Minimum Speed	0.0000145 mm/s	0.00000 "/s
Speed Resolution	0.0000145 mm/s	0.00000 "/s
Encoder Type	None	
Peak Thrust	35 N	7.8 lb
Maximum Continuous Thrust	25 N	5.6 lb
Guide Type	Ball bearing	
Vertical Runout	< 4 µm	< 0.000157 "
Horizontal Runout	< 13 µm	< 0.000512 "
Linear Motion Per Motor Rev	0.3048 mm	0.012 "
Motor Steps Per Rev	200	
Motor Type	Stepper (2 phase)	
Motor Rated Current	240 mA/phase	
Motor Winding Resistance	20.4 ohms/phase	
Inductance	5 mH/phase	
Motor Rated Power	2.35 Watts	
Motor Connection	D-sub 15	
Motor Frame Size	NEMA 08	
Mechanical Drive System	Precision lead screw	
Limit or Home Sensing	Magnetic hall sensor	
Axes of Motion	1	
Mounting Interface	M2 and M3 threaded holes and M4 threaded centre hole	
Compatible Products	AB106, T-LSM	
Operating Temperature Range	0 to 50 degrees C	

RoHS Compliant	Yes
CE Compliant	Yes

Comparison - LSA Series

Part Number	Travel Range	Accuracy (unidirectional)	Maximum Centered Load	Maximum Cantilever Load
LSA10A-T4	10 mm (0.394 ")	18 µm (0.000709 ")	25 N (5.6 lb)	100 N-cm (141.6 oz-in)
LSA25A-T4	25 mm (0.984 ")	24 µm (0.000945 ")	30 N (6.7 lb)	125 N-cm (177.0 oz-in)

Part Number	Pitch	Roll	Yaw	Weight
LSA10A-T4	0.09 degrees (1.571 mrad)	0.03 degrees (0.524 mrad)	0.04 degrees (0.698 mrad)	0.115 kg
LSA25A-T4	0.14 degrees (2.443 mrad)	0.05 degrees (0.873 mrad)	0.12 degrees (2.094 mrad)	0.132 kg